New properties of prolongations of Linear connections on Weil bundles

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Abstract

Let M be a paracompact smooth manifold, A a Weil algebra and M^A the associated Weil bundle. If ∇ is a linear connection on M, we give equivalent definition and the properties of the prolongation ∇^A to M^A equivalent to the prolongation defined by Morimoto. When (M, \mathbf{g}) is a pseudo-riemannian manifold, we show that the symmetric tensor \mathbf{g}^A of type (0,2) defined by Okassa is nondegenerated. At the end, we show that , if ∇ is a Levi-Civita connection on (M, \mathbf{g}) , then ∇^A is torsion-free and \mathbf{g}^A is parallel with respect to ∇^A .

1 Introduction

We recall that, in what follows we denote A, a local algebra (in the sense of André Weil) or simply Weil algebra, M a smooth manifold, $C^{\infty}(M)$ algebra of smooth functions on M and M^A the manifold of infinitely near points of kind A [10]. The triplet (M^A, π, M) is a bundle called bundle of infinitely near points or simply Weil bundle.

If $f: M \longrightarrow \mathbb{R}$ is a smooth function then the application

$$f^A: M^A \longrightarrow A, \xi \longmapsto \xi(f)$$

is also a smooth function . The set, $C^{\infty}(M^A,A)$ of smooth functions on M^A with values on A, is a commutative algebra over A with unit and the application

$$C^{\infty}(M) \longrightarrow C^{\infty}(M^A, A), f \longmapsto f^A$$

is an injective homomorphism of algebras. Then, we have:

$$(f+g)^A = f^A + g^A; \ (\lambda \cdot f)^A = \lambda \cdot f^A; (f \cdot g)^A = f^A \cdot g^A.$$

The map

$$C^{\infty}(M^A) \times A \longrightarrow C^{\infty}(M^A, A), (F, a) \longmapsto F \cdot a : \xi \longmapsto F(\xi) \cdot a$$

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is bilinear and induces one and only one linear map

$$\sigma: C^{\infty}(M^A) \otimes A \longrightarrow C^{\infty}(M^A, A).$$

When $(a_{\alpha})_{\alpha=1,2,...,\dim A}$ is a basis of A and when $(a_{\alpha}^*)_{\alpha=1,2,...,\dim A}$ is a dual basis of the basis $(a_{\alpha})_{\alpha=1,2,...,\dim A}$, the application

$$\sigma^{-1}: C^{\infty}(M^A, A) \longrightarrow A \otimes C^{\infty}(M^A), \varphi \longmapsto \sum_{\alpha=1}^{\dim A} a_{\alpha} \otimes (a_{\alpha}^* \circ \varphi)$$

is an isomorphism of A-algebras. That isomorphism does not depend of a choisen basis and the application

$$\gamma: C^{\infty}(M) \longrightarrow A \otimes C^{\infty}(M^A), f \longmapsto \sigma^{-1}(f^A),$$

is a homomorphism of algebras.

If (U, φ) is a local chart of M with coordinate system $(x_1, ..., x_n)$, the map

$$\varphi^A: U^A \longrightarrow A^n, \xi \longmapsto (\xi(x_1), ..., \xi(x_n))$$

is a bijection from U^A onto an open set of A^n . In addition, if $(U_i, \varphi_i)_{i \in I}$ is an atlas of M^A , then $(U_i^A, \varphi_i^A)_{i \in I}$ is also an atlas of M^A [2].

1.1 Vector fields on M^A

In [6], we gave another characterization of a vector field on M^A through the above theorem and we also give a writing of a vector field on M^A , in coordinate neighborhood system.

Thus,

Theorem 1 The following assertions are equivalent:

- 1. A vector field on M^A is a differentiable section of the tangent bundle (TM^A, π_{M^A}, M^A) .
- 2. A vector field on M^A is a derivation of $C^{\infty}(M^A)$.
- 3. A vector field on M^A is a derivation of $C^{\infty}(M^A, A)$ which is A-linear.
- 4. A vector field on M^A is a linear map $X: C^{\infty}(M) \longrightarrow C^{\infty}(M^A, A)$ such that

$$X(f \cdot g) = X(f) \cdot g^A + f^A \cdot X(g), \quad \text{for any } f, g \in C^{\infty}(M).$$

We verify that the $C^{\infty}(M^A,A)$ -module $\mathfrak{X}(M^A)$ of vecvector field on M^A is a Lie algebra over A.

Theorem 2 The map

$$\mathfrak{X}(M^A) \times \mathfrak{X}(M^A) \longrightarrow \mathfrak{X}(M^A), (X,Y) \longmapsto [X,Y] = X \circ Y - Y \circ X$$

is skew-symmetric A-bilinear and defines a structure of A-Lie algebra over $\mathfrak{X}(M^A)$.

In the following, we look at a vector field as a A-linear maps

$$X: C^{\infty}(M^A, A) \longrightarrow C^{\infty}(M^A, A)$$

such that

$$X(\varphi \cdot \psi) = X(\varphi) \cdot \psi + \varphi \cdot X(\psi), \text{ for any } \varphi, \psi \in C^{\infty}(M^A, A)$$

that is to say

$$\mathfrak{X}(M^A) = Der_A[C^{\infty}(M^A, A)].$$

1.2 Prolongations to M^A of vector fields on M.

Proposition 3 If $\theta: C^{\infty}(M) \longrightarrow C^{\infty}(M)$, is a vector field on M, then there exists one and only one A-linear derivation

$$\theta^A: C^{\infty}(M^A, A) \longrightarrow C^{\infty}(M^A, A),$$

such that $\theta^A(f^A) = [\theta(f)]^A$, for any $f \in C^{\infty}(M)$. Thus, if $\theta, \theta_1, \theta_2$ are vector fields on M and if $f \in C^{\infty}(M)$, then we have:

1.

$$(\theta_1 + \theta_2)^A = \theta_1^A + \theta_2^A; (f \cdot \theta)^A = f^A \cdot \theta^A \text{ and } [\theta_1, \theta_2]^A = \left[\theta_1^A, \theta_2^A\right].$$

2 Prolongation of linear connections on Weil bundles

In this section, if ∇ [3] is a linear connection on M, we give equivalent definition and the properties of the prolongation ∇^A to M^A equivalent to the prolongation $\overline{\nabla}$ defined by Morimoto. When (M, \mathbf{g}) is a pseudo-riemannian manifold, we show that the symmetric tensor \mathbf{g}^A of type (0,2) defined by Okassa is nondegenerated. At the end, we show that , if ∇ is a Levi-Civita connection on (M, \mathbf{g}) , then ∇^A is torsion-free and \mathbf{g}^A is parallel with respect to ∇^A .

According [6], if $X: M^A \longrightarrow TM^A$ is a vector field on M^A and if U is a coordinate neighborhood of M with coordinate neighborhood $(x_1, ..., x_n)$, then there exists some functions $f_i \in C^{\infty}(U^A, A)$ for i = 1, ..., n such that

$$X_{|U^A} = \sum_{i=1}^n f_i \left(\frac{\partial}{\partial x_i^A}\right)^A.$$

When (U,φ) is local chart and $(x_1,...,x_n)$ his local coordinate system. The map

 $U^A \longrightarrow A^n, \xi \longmapsto (\xi(x_1), ..., \xi(x_n)),$

is a diffeomorphism from U^A onto an open set on A^n . As

$$\left(\frac{\partial}{\partial x_i}\right)^A: C^\infty(U^A, A) \longrightarrow C^\infty(U^A, A)$$

is such that $\left(\frac{\partial}{\partial x_i}\right)^A(x_j^A) = \delta_{ij}$, we can denote $\frac{\partial}{\partial x_i^A} = \left(\frac{\partial}{\partial x_i}\right)^A$. If $v \in T_\xi M^A$,

$$v = \sum_{i=1}^{n} v(x_i^A) \frac{\partial}{\partial x_i^A} |_{\xi} .$$

If $X \in \mathfrak{X}(M^A) = Der_A[C^{\infty}(M^A, A)]$, we have

$$X_{|U^A} = \sum_{i=1}^n f_i \frac{\partial}{\partial x_i^A}.$$

with $f_i \in C^{\infty}(U^A, A)$ for i = 1, 2, ..., n.

2.1 Equivalent definitions of derivation laws in $\mathfrak{X}(M^A)$.

In this subsection, we give the definitions of a derivation law in $\mathfrak{X}(M^A) = Der_{\mathbb{R}}[C^{\infty}(M^A)]$ and of a derivation law in $\mathfrak{X}(M^A) = Der_A[C^{\infty}(M^A,A)]$. Let R be an algebra over a commutative field \mathbb{K} . We recall that, a derivation law in a R-module P is a map

$$D: Der_{\mathbb{K}}(R) \longrightarrow End_{\mathbb{K}}(P),$$

such that

- 1. D is R-linear;
- 2. For any $d \in Der_{\mathbb{K}}(R)$, the K-endomorphism $D_d: P \longrightarrow P$ satisfies

$$D_d(r \cdot p) = d(r) \cdot p + r \cdot D_d(p)$$

for any $r \in R$, and any $p \in P$, see [4].

We also recall that, a derivation law in the $C^{\infty}(M)$ -module $\mathfrak{X}(M) = Der_{\mathbb{R}}[C^{\infty}(M)]$ module of vector fields on M is a map

$$D: \mathfrak{X}(M) = Der_{\mathbb{R}}[C^{\infty}(M^A)] \longrightarrow End_{\mathbb{R}}[\mathfrak{X}(M) = Der_{\mathbb{R}}[C^{\infty}(M)]],$$

such that

1. D is $C^{\infty}(M)$ -linear;

2. For any $\theta \in \mathfrak{X}(M)$, the \mathbb{R} -endomorphism $D_{\theta} : \mathfrak{X}(M) \longrightarrow \mathfrak{X}(M)$ satisfies

$$D_{\theta}(f \cdot \mu) = \theta(f) \cdot \mu + f \cdot D_{\theta}(\mu)$$

for any $f \in C^{\infty}(M)$, and any $\mu \in \mathfrak{X}(M^A)$.

That derivation law defines a linear connection on M, see [9]. Now, we say:

Definition 4 A derivation law in $\mathfrak{X}(M^A) = Der_{\mathbb{R}}[C^{\infty}(M^A)]$ is a map

$$D: \mathfrak{X}(M^A) = Der_{\mathbb{R}}[C^{\infty}(M^A)] \longrightarrow End_{\mathbb{R}}[\mathfrak{X}(M^A) = Der_{\mathbb{R}}[C^{\infty}(M^A)]],$$

such that

- 1. D is $C^{\infty}(M^A)$ -linear;
- 2. For any $X \in \mathfrak{X}(M^A)$, the \mathbb{R} -endomorphism $D_X : \mathfrak{X}(M^A) \longrightarrow \mathfrak{X}(M^A)$ satisfies

$$D_X(F \cdot Y) = X(F) \cdot Y + F \cdot D_X(Y)$$

for any $F \in C^{\infty}(M^A)$, and any $Y \in \mathfrak{X}(M^A)$.

Other definition.

In what follows, we denote $\mathfrak{X}(M^A) = Der_A[C^\infty(M^A, A)]$. We denote $End_A[\mathfrak{X}(M^A)]$ the set of A-endomorphisms of $\mathfrak{X}(M^A)$ i.e the set of maps from $\mathfrak{X}(M^A)$ into $\mathfrak{X}(M^A)$ which are linear over A.

Proposition 5 The set $End_A[\mathfrak{X}(M^A)]$ is a $C^{\infty}(M^A, A)$ -module.

Definition 6 A derivation law in $\mathfrak{X}(M^A) = Der_A[C^{\infty}(M^A, A)]$. is a map

$$D: \mathfrak{X}(M^A) \longrightarrow End_{\mathbb{R}}\left[\mathfrak{X}(M^A)\right],$$

such that:

- 1. D is $C^{\infty}(M^A, A)$ -linear;
- 2. For any $X \in \mathfrak{X}(M^A)$, the A-endomorphism $D_X : \mathfrak{X}(M^A) \longrightarrow \mathfrak{X}(M^A)$ verifies

$$D_X(\varphi \cdot Y) = X(\varphi) \cdot Y + \varphi \cdot D_X(Y)$$

for any $\varphi \in C^{\infty}(M^A)$, and any $Y \in \mathfrak{X}(M^A)$.

2.2 The new statement of the Morimoto's prolongation of a linear connection on M.

Theorem 7 If ∇ is a linear connection on M, then there exists one and only one linear application

$$\nabla^A: \mathfrak{X}(M^A) \longrightarrow End_A[\mathfrak{X}(M^A)], X \longmapsto \nabla^A_X$$

such that

$$\nabla_{\theta^A}^A \eta^A = (\nabla_\theta \eta)^A \,,$$

for any $\theta, \eta \in \mathfrak{X}(M)$.

Proof. If $X \in \mathfrak{X}(M^A) = Der_A[C^{\infty}(M^A, A)]$, then

$$X(f^A) = \sum_{\alpha=1}^{\dim A} X'(a_{\alpha}^* \circ f^A) \cdot a_{\alpha} = \sum_{\alpha=1}^{\dim A} X(a_{\alpha}^* \circ f^A) \cdot a_{\alpha}$$

with $X^{'} \in \mathfrak{X}(M^A) = Der_A[C^{\infty}(M^A)].$

$$\overline{\nabla}: \mathfrak{X}(M^A) = Der_{\mathbb{R}}[C^{\infty}(M^A)] \longrightarrow End_{\mathbb{R}}\left[\mathfrak{X}(M^A) = Der_{\mathbb{R}}[C^{\infty}(M^A)]\right]$$

be the Morimoto's prolongation to M^A of the linear connection ∇ on M. We denote

$$\nabla^A : \mathfrak{X}(M^A) = Der_A[C^\infty(M^A, A)] \longrightarrow End_A\left[\mathfrak{X}(M^A) = Der_A[C^\infty(M^A, A)]\right]$$

the same derivation law in $\mathfrak{X}(M^A) = Der_A[C^{\infty}(M^A, A)]$. Thus for any $\theta, \eta \in \mathfrak{X}(M)$, we have:

$$\left[\nabla_{\theta^{A}}^{A}\eta^{A}\right](f^{A}) = \sum_{\alpha=1}^{\dim A} \left[\nabla_{\theta^{A}}^{A}\eta^{A}\right]'(a_{\alpha}^{*} \circ f^{A}) \cdot a_{\alpha} = \sum_{\alpha=1}^{\dim A} \left[\nabla_{(\theta^{A})'}^{A}(\eta^{A})'\right](a_{\alpha}^{*} \circ f^{A}) \cdot a_{\alpha}$$

$$= \sum_{\alpha=1}^{\dim A} \left[(\nabla_{\theta}\eta)^{A}\right]'(a_{\alpha}^{*} \circ f^{A}) \cdot a_{\alpha}$$

$$= \sum_{\alpha=1}^{\dim A} \left[(\nabla_{\theta}\eta)^{A}\right](a_{\alpha}^{*} \circ f^{A}) \cdot a_{\alpha}$$

$$= \left[(\nabla_{\theta}\eta)^{A}\right](f^{A}),$$

for any $f \in C^{\infty}(M)$, hence

$$\nabla^A_{\theta^A} \eta^A = (\nabla_\theta \eta)^A.$$

2.2.1 Torsion of ∇^A .

When ∇ is a linear connection on M, we denote T_{∇} the torsion of ∇ .

Proposition 8 If ∇ is a linear connection on M, then the torsion of ∇^A

$$T_{\nabla^A}: \mathfrak{X}(M^A) \times \mathfrak{X}(M^A) \longrightarrow \mathfrak{X}(M^A), (X,Y) \longmapsto = \nabla_X^A Y - \nabla_Y^A X - [X,Y],$$

is a skew-symmetric $C^{\infty}(M^A, A)$ -bilinear.

Proof.

1. For all vector fields $X, Y, Z \in \mathfrak{X}(M^A)$, we have:

$$\begin{split} T_{\nabla^A}(X+Y,Z) &= \nabla^A_{(X+Y)}Z - \nabla^A_Z(X+Y) - [X+Y,Z] \\ &= \nabla^A_XZ + \nabla^A_YZ - \nabla^A_Z(X) - \nabla^A_Z(Y) - [X,Z] - [Y,Z] \\ &= \nabla^A_XZ - \nabla^A_Z(X) - [X,Z] + \nabla^A_YZ - \nabla^A_Z(Y) - [Y,Z] \\ &= T_{\nabla^A}(X,Z) + T_{\nabla^A}(Y,Z). \end{split}$$

2. For any vector field $X \in \mathfrak{X}(M^A)$, we have:

$$T_{\nabla^A}(X,X) = \nabla_X^A X - \nabla_X^A X - [X,X]$$

= 0.

3. For any vector fields $X \in \mathfrak{X}(M^A)$ and for any $\varphi \in C^{\infty}(M^A, A)$, we have

$$\begin{split} T_{\nabla^A}(X,\varphi\cdot Y) &= \nabla_X^A\varphi\cdot Y - \nabla_{\varphi\cdot Y}^A(X) - [X,\varphi\cdot Y] \\ &= X(\varphi)\cdot Y + \varphi\cdot \nabla_X^AY - \varphi\cdot \nabla_Y^AX - X(\varphi)\cdot Y - \varphi\cdot [Y,X] \\ &= \varphi\cdot \nabla_X^AY - \varphi\cdot \nabla_Y^AX - \varphi\cdot [Y,X] \\ &= \varphi\cdot \left(\nabla_X^AY - \nabla_Y^AX - [Y,X]\right) \\ &= \varphi\cdot T_{\nabla^A}(X,Y). \end{split}$$

Therefore the torsion T_{∇^A} is skew-symmetric $C^{\infty}(M^A, A)$ -bilinear.

Proposition 9 For any $X, Y \in \mathfrak{X}(M^A)$, and if U is coordonate neighborhood of M, then

$$T_{\nabla^A_{|U^A}}(X_{|U^A},Y_{|U^A}) = [T_{\nabla^A}(X,Y)]_{|U^A} \ .$$

Proposition 10 If ∇ is a linear connection on M, then

$$T_{\nabla^A}(\theta^A, \eta^A) = [T_{\nabla}(\theta, \eta)]^A$$

for any $\theta, \eta \in \mathfrak{X}(M)$.

Proof. For any $\theta, \eta \in \mathfrak{X}(M)$, we have:

$$T_{\nabla^A}(\theta^A, \eta^A) = \nabla_{\theta^A}^A \eta^A - \nabla_{\eta^A}^A \theta^A - [\theta^A, \eta^A]$$
$$= [\nabla_{\theta} \eta]^A - [\nabla_{\eta} \theta]^A - [\theta, \eta]^A$$
$$= (\nabla_{\theta} \eta - \nabla_{\eta} \theta - [\theta, \eta]^A)$$
$$= [T_{\nabla}(\theta, \eta)]^A.$$

Corollary 11 If the linear connection ∇ is torsion-free, then ∇^A is also torsion-free

Proof. Let X,Y be two vector fields M^A and U a coordinate neighborhood of M^A . Then

$$X_{|U^A} = \sum_{i=1}^n f_i \frac{\partial}{\partial x_i^A}; Y_{|U^A} = \sum_{j=1}^n g_j \frac{\partial}{\partial x_j^A}$$

and, we have:

$$\begin{split} [T_{\nabla^A}(X,Y)]_{|U^A} &= T_{\nabla^A_{|U^A}}(X_{|U^A},Y_{|U^A}) \\ &= T_{\nabla^A_{|U^A}}\left(\sum_{i=1}^n f_i \frac{\partial}{\partial x_i^A}, \sum_{j=1}^n g_j \frac{\partial}{\partial x_j^A}\right) \\ &= \sum_{ij=1}^n f_i g_j T_{\nabla^A_{|U^A}}\left(\frac{\partial}{\partial x_i^A}, \frac{\partial}{\partial x_j^A}\right) \\ &= \sum_{ij=1}^n f_i g_j T_{\nabla^A_{|U^A}}\left(\left(\frac{\partial}{\partial x_i}\right)^A, \left(\frac{\partial}{\partial x_j}\right)^A\right) \\ &= \sum_{ij=1}^n f_i g_j \left[T_{\nabla_{|U}}\left(\frac{\partial}{\partial x_i}, \frac{\partial}{\partial x_j}\right)\right]^A, \end{split}$$

as ∇ is torsion-free that is to say $T_{\nabla}=0,$ hence $[T_{\nabla^A}(X,Y)]_{|U^A}=0.$ Consequently

$$T_{\nabla^A} = 0.$$

2.3 Prolongation of the Levi-Civita connection.

In this subsection we consider (M, g) a pseudo-riemannian manifold, in what follows we study the prolongation of connections to M^A deduce from the Levi-Civita connection on M.

Proposition 12 [7] Let $g: \mathfrak{X}(M) \times \mathfrak{X}(M) \longrightarrow C^{\infty}(M)$ be a symmetric tensor of type (0,2) on M. There exists one and only one symmetric tensor g^A of type (0,2) on M^A with value in A such that $g^A(a \cdot \eta^A, b \cdot \theta^A) = ab \cdot [g(\eta, \theta)]^A$ for any $a, b \in A$ and $\eta, \theta \in \mathfrak{X}(M)$.

Following [?], we state:

Proposition 13 When (M, g) a pseudo-riemannian manifold, then there exists one and only one $C^{\infty}(M^A, A)$ -nondegenerated symmetric bilineat form

$$g^A: \mathfrak{X}(M^A) \times \mathfrak{X}(M^A) \longrightarrow C^{\infty}(M^A, A)$$

such that for any vector fields η and θ on M,

$$g^{A}(\eta^{A}, \theta^{A}) = [g(\eta, \theta)]^{A}$$

where η^A and θ^A mean prolongations to M^A of vector fields η and θ .

Proof. It is a matter here to show only the nondegeneracy of g^A , the proof is in the same way as in [?].

Therefore g^A is a pseudo-riemannian manifold on M^A and confers to M^A the structure of pseudo-riemannian manifold.

Proposition 14 For any $X \in \mathfrak{X}(M^A)$, the map

$$\nabla_X^A g^A : \mathfrak{X}(M^A) \times \mathfrak{X}(M^A) \longrightarrow C^\infty(M^A, A)$$

such that

$$\nabla_X^A \mathbf{g}^A(Y,Z) = X \left[\mathbf{g}^A(Y,Z) \right] - \mathbf{g}^A \left(\nabla_X^A(Y),Z \right) - \mathbf{g}^A \left(Y, \nabla_X^A Z \right)$$

for any $Y, Z \in \mathfrak{X}(M^A)$ is a symmetric $C^{\infty}(M^A, A)$ -bilinear form.

Proof.

1. For any $X, Y \in \mathfrak{X}(M^A)$, we have:

$$\begin{split} \nabla_X^A \mathbf{g}^A(Y,Z) &= X \left[\mathbf{g}^A(Y,Z) \right] - \mathbf{g}^A \left(\nabla_X^A(Y),Z \right) - \mathbf{g}^A \left(Y, \nabla_X^A Z \right) \\ &= X \left[\mathbf{g}^A(Z,Y) \right] - \mathbf{g}^A \left(Z, \nabla_X^A(\varphi \cdot Y) \right) - \mathbf{g}^A \left(\nabla_X^A Z, \varphi \cdot Y \right) \\ &= \nabla_X^A \mathbf{g}^A(Z,Y), \end{split}$$

hence $\nabla_X^A \mathbf{g}^A$ is symmetric.

2. Let Y_1, Y_2 and Z be the vector fields in $\mathfrak{X}(M^A)$, we have:

$$\begin{split} \nabla_{X}^{A} \mathbf{g}^{A} \left(Y_{1} + Y_{2}, Z \right) &= X \left[g^{A} (Y_{1} + Y_{2}, Z) \right] - \mathbf{g}^{A} \left(\nabla_{X}^{A} (Y_{1} + Y_{2}), Z \right) - \mathbf{g}^{A} \left(Y_{1} + Y_{2}, \nabla_{X}^{A} Z \right) \\ &= X \left[\mathbf{g}^{A} (Y_{1}, Z) + g^{A} (Y_{2}, Z) \right] - \mathbf{g}^{A} \left(\nabla_{X}^{A} Y_{1} + \nabla_{X}^{A} Y_{2}, Z \right) - \mathbf{g}^{A} \left(Y_{1}, \nabla_{X}^{A} Z \right) \\ &- \mathbf{g}^{A} \left(Y_{2}, \nabla_{X}^{A} Z \right) \\ &= X \left[g^{A} (Y_{1}, Z) \right] + X \left[g^{A} (Y_{2}, Z) \right] - g^{A} \left(\nabla_{X}^{A} Y_{1}, Z \right) - \mathbf{g}^{A} \left(\nabla_{X}^{A} Y_{2}, Z \right) \\ &- \mathbf{g}^{A} \left(Y_{1}, \nabla_{X}^{A} Z \right) - \mathbf{g}^{A} \left(Y_{2}, \nabla_{X}^{A} Z \right) \\ &= X \left[\mathbf{g}^{A} (Y_{1}, Z) \right] - \mathbf{g}^{A} \left(\nabla_{X}^{A} Y_{1}, Z \right) - \mathbf{g}^{A} \left(Y_{1}, \nabla_{X}^{A} Z \right) + X \left[\mathbf{g}^{A} (Y_{2}, Z) \right] \\ &- \mathbf{g}^{A} \left(\nabla_{X}^{A} Y_{2}, Z \right) - \mathbf{g}^{A} \left(Y_{2}, \nabla_{X}^{A} Z \right) \\ &= \nabla_{X}^{A} \mathbf{g}^{A} \left(Y_{1}, Z \right) + \nabla_{X}^{A} \mathbf{g}^{A} (Y_{2}, Z) \, . \end{split}$$

3. Let Y and Z the vector fields in $\mathfrak{X}(M^A)$ and $\varphi \in C^{\infty}(M^A, A)$, we have:

$$\begin{split} \nabla_X^A \mathbf{g}^A \left(\varphi \cdot Y, Z \right) &= X \left[\mathbf{g}^A \left(\varphi \cdot Y, Z \right) \right] - \mathbf{g}^A \left(\nabla_X^A (\varphi \cdot Y), Z \right) - \mathbf{g}^A \left(\varphi \cdot Y, \nabla_X^A Z \right) \\ &= X(\varphi) \cdot \mathbf{g}^A (Y, Z) + \varphi \cdot X \left[\mathbf{g}^A (Y, Z) \right] - \mathbf{g}^A \left(X(\varphi) \cdot Y, Z \right) + \varphi \cdot \mathbf{g}^A \left(\nabla_X^A Y, Z \right) \\ &- \varphi \cdot \mathbf{g}^A \left(Y, \nabla_X^A Z \right) \\ &= X(\varphi) \cdot \mathbf{g}^A (Y, Z) + \varphi \cdot X \left[\mathbf{g}^A (Y, Z) \right] - X(\varphi) \cdot \mathbf{g}^A (Y, Z) - \varphi \cdot \mathbf{g}^A \left(\nabla_X^A Y, Z \right) \\ &- \varphi \cdot \mathbf{g}^A \left(Y, \nabla_X^A Z \right) \\ &= \varphi \cdot X \left[\mathbf{g}^A (Y, Z) \right] - \varphi \cdot \mathbf{g}^A \left(\nabla_X^A Y, Z \right) - \varphi \cdot \mathbf{g}^A \left(Y, \nabla_X^A Z \right) \\ &= \varphi \cdot \nabla_X^A \mathbf{g}^A (Y, Z). \end{split}$$

Therefore, the map $\nabla_X^A \mathbf{g}^A$ is a symmetric $C^{\infty}(M^A,A)$ -bilinear form.

Proposition 15 If ∇ is a linear connection on the pseudo-riemannian manifold (M, \mathbf{g}) , then we have:

$$\nabla_{\theta^A}^A \mathbf{g}^A \left(\mu_1^A, \mu_2^A \right) = \left[\nabla_{\theta} \mathbf{g} \left(\mu_1, \mu_2 \right) \right]^A$$

for any $\theta, \mu_1, \mu_2 \in \mathfrak{X}(M^A)$.

Proof. for any $\theta, \mu_1, \mu_2 \in \mathfrak{X}(M^A)$, we have:

$$\begin{split} \nabla_{\theta^{A}}^{A} \mathbf{g}^{A}(\mu_{1}^{A}, \mu_{2}^{A}) &= \theta^{A} \left[\mathbf{g}^{A}(\mu_{1}^{A}, \mu_{2}^{A}) \right] - \mathbf{g}^{A} \left(\nabla_{\theta^{A}}^{A} \mu_{1}^{A}, \mu_{2}^{A} \right) - \mathbf{g}^{A} \left(\mu_{1}^{A}, \nabla_{\theta^{A}}^{A} \mu_{2}^{A} \right) \\ &= \theta^{A} \left[(\mathbf{g}(\mu_{1}, \mu_{2}))^{A} \right] - \left[\mathbf{g} \left(\nabla_{\theta} \mu_{1}, \mu_{2} \right) \right]^{A} - \left[\mathbf{g} \left(\mu_{1}, \nabla_{\theta} \mu_{2} \right) \right]^{A} \\ &= \left[\theta(\mathbf{g}(\mu_{1}, \mu_{2})) \right]^{A} - \left[\mathbf{g} \left(\nabla_{\theta} \mu_{1}, \mu_{2} \right) \right]^{A} - \left[\mathbf{g} \left(\mu_{1}, \nabla_{\theta} \mu_{2} \right) \right]^{A} \\ &= \left[\theta(\mathbf{g}(\mu_{1}, \mu_{2})) - \mathbf{g}(\nabla_{\theta} \mu_{1}, \mu_{2}) - \mathbf{g}(\mu_{1}, \nabla_{\theta} \mu_{2}) \right]^{A} \\ &= \left[\nabla_{\theta} \mathbf{g}(\mu_{1}, \mu_{2}) \right]^{A}. \end{split}$$

Proposition 16 For any $X, Y, Z \in \mathfrak{X}(M^A)$, and if U is coordinate neighborhood of M, then

$$\left[\left(\nabla^A_{|U^A} \right)_{|U^A} \mathbf{g}^A_{|U^A} \right) \right] \left(X_{|U^A}, \, Y_{|U^A} \right) = \left[\nabla^A_X \mathbf{g}^A(Y, Z) \right]_{|U^A}.$$

Corollary 17 If ∇ is the Levi-Civita connection on the pseudo-riemannian manifold (M, g), then we have:

$$\nabla_X^A \mathbf{g}^A = 0$$

for any $X \in \mathfrak{X}(M^A)$.

Proof. Let X, Y, Z be vector fields M^A and U a coordinate neighborhood of M^A . Then

$$X_{|U^A} = \sum_{i=1}^n f_i \frac{\partial}{\partial x_i^A}; \ Y_{|U^A} = \sum_{j=1}^n g_j \frac{\partial}{\partial x_j^A}; \ Z_{|U^A} = \sum_{k=1}^n h_k \frac{\partial}{\partial x_k^A}.$$

Thus, we have:

$$\begin{split} \left[\nabla_{X}^{A}\mathbf{g}^{A}(Y,Z)\right]_{|U^{A}} &= \left[\left(\nabla_{|U^{A}}^{A}\right)_{X_{|U^{A}}}\right)\mathbf{g}_{|U^{A}}^{A}\left(Y_{|U^{A}},Z_{|U^{A}}\right)\right] \\ &= \left(\left(\nabla_{|U^{A}}^{A}\right)_{\left(\sum_{i=1}^{n}f_{i}}\frac{\partial}{\partial x_{i}^{A}}\right)}\mathbf{g}_{|U^{A}}^{A}\right)\left(\sum_{j=1}^{n}g_{j}\frac{\partial}{\partial x_{j}^{A}},\sum_{k=1}^{n}h_{k}\frac{\partial}{\partial x_{k}^{A}}\right) \\ &= \sum_{ijk=1}^{n}f_{i}g_{j}h_{k}\left(\left(\nabla_{|U^{A}}^{A}\right)_{\left(\frac{\partial}{\partial x_{i}}\right)}\mathbf{g}_{|U^{A}}^{A}\right)\left(\frac{\partial}{\partial x_{j}^{A}},\frac{\partial}{\partial x_{k}^{A}}\right) \\ &= \sum_{ijk=1}^{n}f_{i}g_{j}h_{k}\left(\left(\nabla_{|U^{A}}^{A}\right)_{\left(\frac{\partial}{\partial x_{i}}\right)}^{A}\mathbf{g}_{|U^{A}}^{A}\right)\left(\left(\frac{\partial}{\partial x_{j}}\right)^{A},\left(\frac{\partial}{\partial x_{k}}\right)^{A}\right) \\ &= \sum_{ijk=1}^{n}f_{i}g_{j}h_{k}\left(\left(\nabla_{|U^{A}}\right)_{\left(\frac{\partial}{\partial x_{i}}\right)}^{A}\mathbf{g}_{|U^{A}}\right)\left(\frac{\partial}{\partial x_{j}},\frac{\partial}{\partial x_{k}}\right)^{A}. \end{split}$$

As ∇ is the Levi-Civita connection, then $\nabla_{\theta} g = 0$, hence $\left[\nabla_X^A g^A(Y, Z)\right]_{|U^A} = 0$. It follows that,

$$\nabla_X^A \mathbf{g}^A = 0.$$

Theorem 18 If ∇ is a Levi-Civita connection on a pseudo-riemannian manifold (M, g), then ∇^A verifies the following properties:

- 1. $T_{\nabla^A} = 0$;
- 2. $\nabla_X^A g^A = 0$ for any $X \in \mathfrak{X}(M^A)$.

Proof. The proof is deduced from the corollary ?? and corollary ??. \blacksquare Thus ∇^A is a Levi-Civita connection on the pseudo-riemannian manifold (M^A, \mathbf{g}^A) .

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